Parallel DBSCAN Clustering Algorithm using Apache Spark

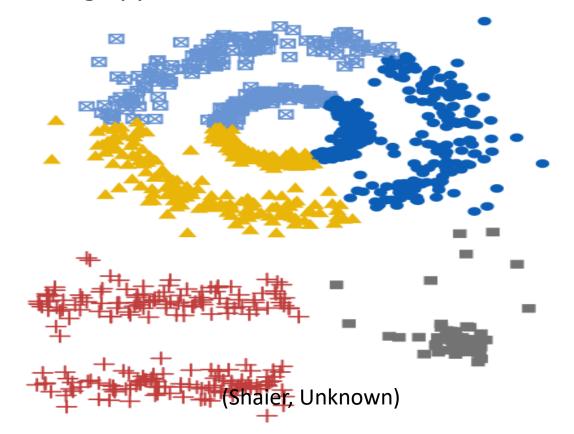
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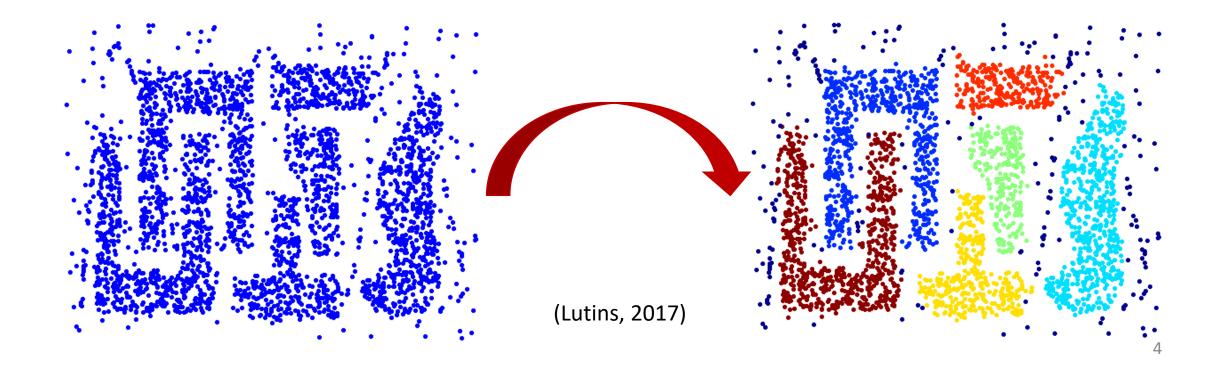
Overview

- Introduction to DBSCAN algorithm
- Problem definition
- Introduction to MapReduce algorithm
- Description of Apache Spark
- A novel scalable DBSCAN algorithm with Spark
- Conclusion
- Question

- Density-based spatial clustering
- An unsupervised learning data clustering approach



- Discover clusters of arbitrary shape and size
- Resistant to noise



Density: number of points within a specified radius (Eps)

Two parameters:

• Epsilon (Eps): Maximum radius of the neighbourhood

• MinPts: Minimum number of points in an Epsilon-neighbourhood of that

point

$$MinPts = 4$$

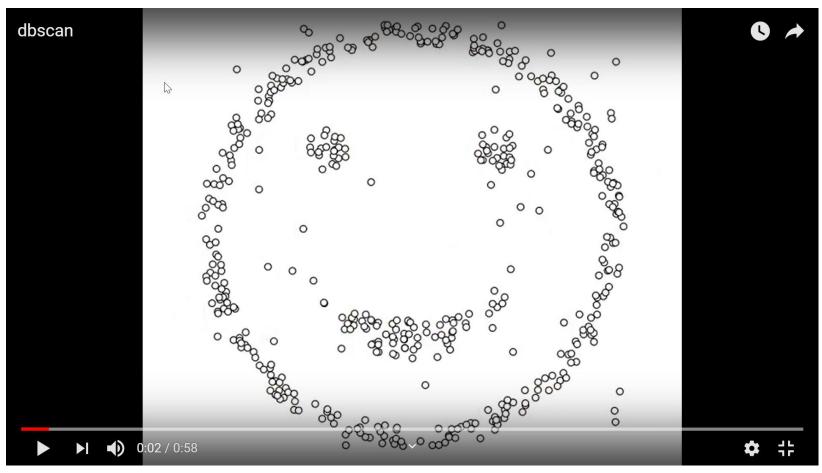
$$Eps = 1 cm$$

- 1. Select an arbitrary point **p**, insert that to a queue
- 2. Retrieve all neighbor points of **p** wrt **Eps**
- 3. If the number of points are greater than or equal to **MinPts**, a cluster is formed, all neighbours are inserted to the queue
- 4. Repeate steps 2 to 3 for all points in the queue
- 5. Continue the process until all of the points have been processed
- 6. Noise points do not belong to any clusters

MinPts = 4

Eps = 1 cm

q



(source: https://www.youtube.com/watch?v=h53WMIImUuc)

Problem

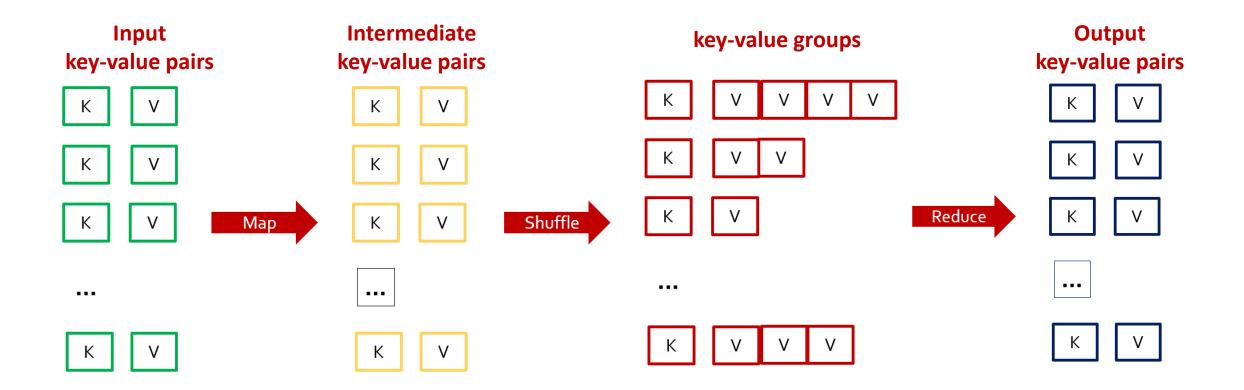


- Algorithm goes through each point of the database multiple times
- O(nlog(n)) Best case, using kd-tree
- O(n²) Worst case

MapReduce

- MapReduce is a framework for data processing
- The goal is to process massive data by connecting many cluster nodes to work in parallel
- Map function and reduce function suppose to be programmed
- In MapReduce data elements are always structured as key-value (i.e., (K, V)) pairs

MapReduce



MapReduce

• Rather than sending data to where the application or logic resides, the logic is executed on the server where the data already resides

A work performed by each task is done independetly

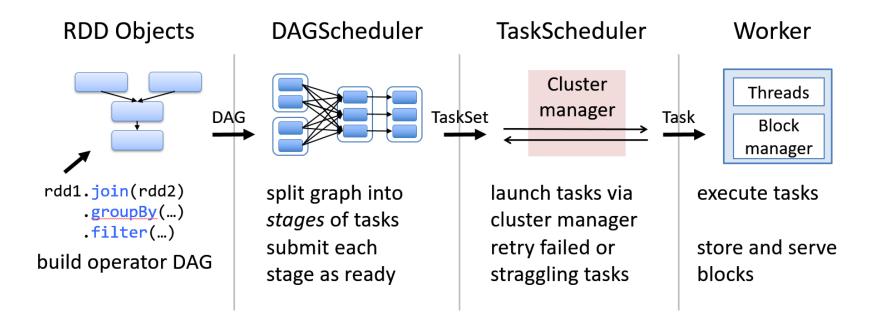
Hadoop

- Open source software framework designed for storage and processing of large scale data on clusters
- Use multiple machines for a single task
- Divided into Data Nodes and Compute Nodes
- At compute time, data is copied to the Compute Nodes
- A master program allocates work to individual nodes

Spark



 Not limited to map and reduce function, defines a large set of operations (transformations & actions)



A novel scalable DBSCAN algorithm with Spark

SEEDs: points that do not belong to the current partition

- shuffle operations are prevented which costs a lot
- Generates the same results as the serial algorithm

Range: 0 -- 2499 Status: unfinished c[0]5 6 3000 11 223 2300 23 45 1000

Range: 2500 -- 4999 Status: unfinished

c[5] 3000 2501 2800 2600 3401 3678

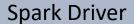
> Number of points: 5000 Number of partitions: 2 (a)

> > Range: 0 -- 4999 Status: finished

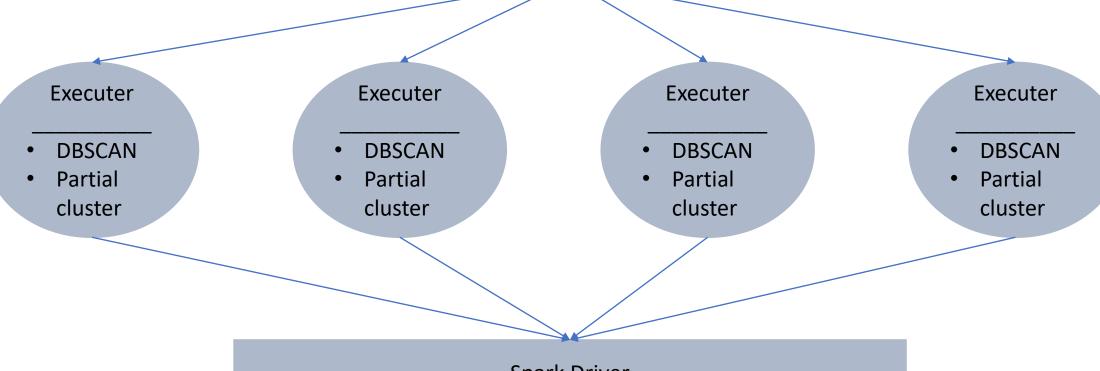
c[0]3000 11 223 2300 23 45 1000 3401 3678

> Number of points: 5000 Number of partitions: 2 (b)

> > (Han, et.al, 2016)



- Generate RDDs from the data
- Transform the existing RDDs into RDDs with Point type
 - distribute those RDDs into executors



Spark Driver

- Dig out SEEDs and identify master partial clusters
 - Merge clusters based on seeds

Question

• What was is the time complexity of DBSCAN?



Question

As I explained we can use Kd-tree algorithm in order to reduce the time complexity of the DBSCAN to (nlog(n))

• Who can explain how does RD-tree work on two dimension?



References

- Martin Ester, Hans-Peter Kriegel, Jörg Sander, Xiaowei Xu, et al. A density-based algorithm for discovering clusters in large spatial databases with noise. In Kdd, volume 96, pages 226–231, 1996
- Dianwei Han, Ankit Agrawal, Wei-Keng Liao, and Alok Choudhary. 2016. A Novel Scalable DBSCAN Algorithm with Spark. In Proc. 2016 IEEE Int'l Sympo. on Parallel and Distributed Processing. 1393–1402
- Kyuseok Shim. Mapreduce algorithms for big data analysis. Proceedings of the VLDB Endowment, 5(12):2016–2017, 2012.

